

# Fixpoint Theory – Upside Down

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(Work in progress)

## Upper and Lower Bounds for Fixpoints

Let  $f: \mathbb{L} \rightarrow \mathbb{L}$  be a monotone function over a complete lattice  $\mathbb{L}$ . By Knaster-Tarski it has a **least fixpoint**  $\mu f$  and a **greatest fixpoint**  $\nu f$ .

Any **pre-fixpoint** ( $\ell \in \mathbb{L}$  with  $f(\ell) \sqsubseteq \ell$ ) is an **upper bound** for  $\mu f$  and any **post-fixpoint** ( $\ell \in \mathbb{L}$  with  $\ell \sqsubseteq f(\ell)$ ) is a **lower bound** for  $\nu f$ .

### Challenge

Can we find suitable witnesses guaranteeing that  $\ell \in \mathbb{L}$  is a **lower bound** for  $\mu f$  or an **upper bound** for  $\nu f$ ?

**Applications:** termination probability, behavioural distances, bisimilarity ...

## Aims of Working Group 1.3

*To support and promote the systematic development of the fundamental **mathematical theory** of systems specification. To investigate the theory of formal models for systems specification, development, transformation and **verification**.*

↪ **fixpoints** as a fundamental mathematical technique for system verification (reachability analysis, dataflow analysis, model-checking, ...)

# Fixpoint Theory

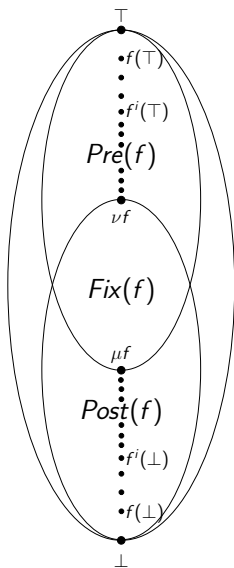
## Solution techniques

- The **Knaster-Tarski theorem** guarantees the existence of least and greatest fixpoints for monotone functions
- We have the following **proof rules for upper and lower bounds**:

$$\frac{f(\ell) \sqsubseteq \ell}{\mu f \sqsubseteq \ell} \qquad \frac{\ell \sqsubseteq f(\ell)}{\ell \sqsubseteq \nu f}$$

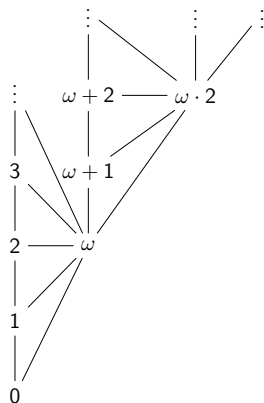
- **Kleene iteration**: whenever  $f$  is (co-)continuous
  - $\mu f = \bigsqcup_{i \in \mathbb{N}} f^i(\perp)$  (least fixpoint)
  - $\nu f = \bigsqcap_{i \in \mathbb{N}} f^i(\top)$  (greatest fixpoint)

# Fixpoint Theory



If  $f$  is *not* (co-)continuous:

$\rightsquigarrow$  Kleene iteration over the ordinals  
(beyond  $\omega$ )



# Fixpoint Theory

The following proof rules (based on Kleene iteration) provide guarantees for the opposite bounds. By  $i$  we denote some ordinal.

$$\frac{\ell \sqsubseteq f^i(\perp)}{\ell \sqsubseteq \mu f} \qquad \frac{f^i(\top) \sqsubseteq \ell}{\nu f \sqsubseteq \ell}$$

This is related to [ranking](#) functions that are e.g. used in termination analysis.

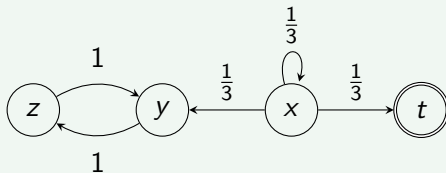
**Problems:** there is no straightforward [witness](#) that guarantees these bounds, (ordinals are involved)

**Our aim:** provide proof rules of the form

$$\frac{\ell \sqsubseteq f(\ell) + \text{extra conditions}}{\ell \sqsubseteq \mu f} \qquad \frac{f(\ell) \sqsubseteq \ell + \text{extra conditions}}{\nu f \sqsubseteq \ell}$$

# Termination Probability

What is the probability of terminating from state  $x$ ?



# Termination Probability

## Markov chain

$(X, T, (p_x)_{x \in X \setminus T})$  where

- $X$  is the finite state space,
- $T \subseteq X$  are the terminal states and
- $p_x: X \rightarrow [0, 1]$  is a probability distribution

## Termination probability as least fixpoint

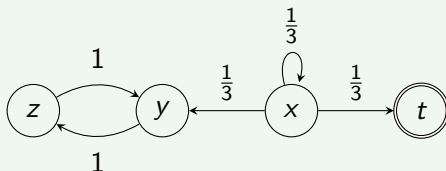
Termination probability given by  $\mu f$  where  $f: [0, 1]^X \rightarrow [0, 1]^X$  and for  $a: X \rightarrow [0, 1]$ ,  $x \in X$ :

$$f(a)(x) = \begin{cases} 1 & \text{if } x \in T \\ \sum_{y \in X} p_x(y) \cdot a(y) & \text{otherwise} \end{cases}$$



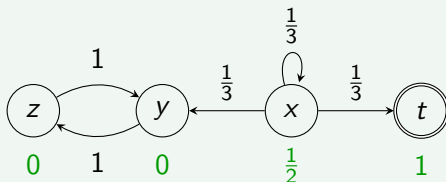
# Termination Probability

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# Termination Probability

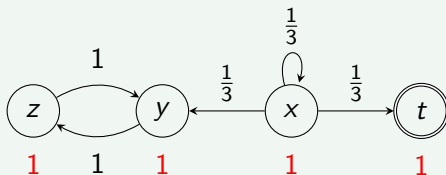
What is the probability of terminating from state  $x$ ?



Least fixpoint, giving the termination probability for  $x$

# Termination Probability

What is the probability of terminating from state  $x$ ?



A different fixpoint, not providing a lower bound for the termination probability of  $x$

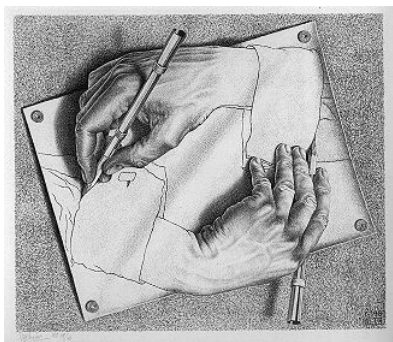
# Termination Probability

We can not trust a **fixpoint** or **pre-fixpoint** to give us a lower bound on the termination probability (given by a *least* fixpoint).

▷ Can we **detect** those fixpoints that are not least fixpoints?

Where is the culprit?

**In the example:**  $y$  and  $z$  convince each other incorrectly (!) that they have termination probability 1  $\rightsquigarrow$  **vicious cycle**



# Termination Probability

**Idea:** compute the set of states that still has some “wiggle room” or “slack”. That is, those states that can say:

*“If all my successors would reduce their value by  $\delta$ , I could also reduce my value by  $\delta$ .”*

This can be computed as a **greatest fixpoint on a finite set**  $\mathcal{P}(X)$  (instead of the infinite lattice that we considered before).

If the function is sufficiently well-behaved and this set (= greatest fixpoint) is **empty**

$\Rightarrow$  we know that we have **reached the least fixpoint** (respectively a pre-fixpoint below the least fixpoint).

## Abstractions for Determining the “Wiggle Room”

We use **Galois connections** (pairs of **abstraction** and **concretization**) in order to determine the “wiggle room” or “slack” of a fixpoint.

### Requirements

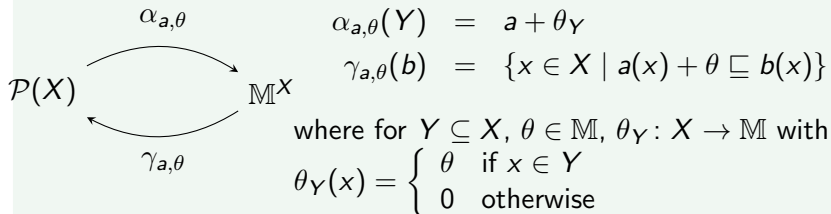
The lattice is of the form  $\mathbb{L} = \mathbb{M}^X$  (set of functions of the form  $X \rightarrow \mathbb{M}$ ), where

- $X$  finite
- $\mathbb{M}$  is a **totally ordered lattice living in a group** (inverses: we can add and subtract!)

We will now consider the dual problems: given  $f: \mathbb{M}^X \rightarrow \mathbb{M}^X$  and  $a: X \rightarrow \mathbb{M}$

- assume that  $f(a) = a$ . Is  $a$  the greatest fixpoint?
- assume that  $f(a) \sqsubseteq a$ . Is  $a$  above the greatest fixpoint?

# Abstractions for Determining the “Wiggle Room”

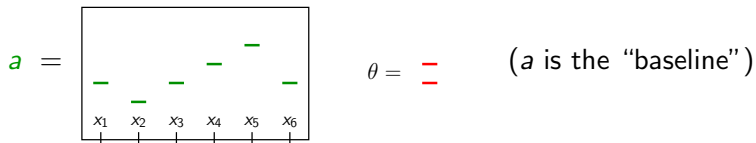


[To be more precise:

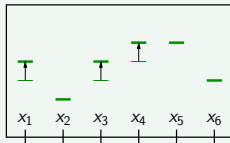
- $\mathbb{M}^X$  should be replaced by  $\{b: X \rightarrow \mathbb{M} \mid a \sqsubseteq b \sqsubseteq a + \theta\}$
- $f$  restricts to this set whenever  $f(a + \theta) \sqsubseteq f(a) + \theta$   
(**Condition 1**)

]

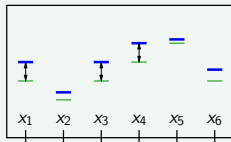
# Abstractions for Determining the “Wiggle Room”



$$\alpha_{a,\theta}: Y = \{x_1, x_3, x_4\} \mapsto$$



$$\gamma_{a,\theta}: b =$$



$$\mapsto Y = \{x_1, x_3, x_4\}$$



# Abstractions for Determining the “Wiggle Room”

## Galois connection

$\langle \alpha_{a,\theta}, \gamma_{a,\theta} \rangle$  satisfy the properties of a **Galois connection**:

- $\alpha_{a,\theta}, \gamma_{a,\theta}$  are monotone
- $id_{\mathcal{P}(X)} \subseteq \gamma_{a,\theta} \circ \alpha_{a,\theta}$
- $\alpha_{a,\theta} \circ \gamma_{a,\theta} \subseteq id_{M^X}$

# Galois Connections and Fixpoints

$$f^\# = \gamma \circ f \circ \alpha \hookrightarrow \mathbb{A} \begin{array}{c} \xrightarrow{\alpha} \\ \xleftarrow{\gamma} \end{array} \mathbb{C} \hookrightarrow f$$

We have  $\nu f^\# = \gamma(\nu f)$  whenever

- $\gamma \circ f \sqsubseteq f^\# \circ \gamma = \gamma \circ f \circ \alpha \circ \gamma$   
(equivalent to  $\alpha \circ \gamma \circ f \sqsubseteq f \circ \alpha \circ \gamma$ )

(see also [Cousot/Cousot], [Bonchi/Ganty/Giacobazzi/Pavlovic])

# Galois Connections and Fixpoints

In our setting:

$$f_{a,\theta}^\# = \gamma_{a,\theta} \circ f \circ \alpha_{a,\theta} \quad \begin{array}{c} \curvearrowright \\ \text{P}(X) \end{array} \quad \begin{array}{c} \xrightarrow{\alpha_{a,\theta}} \\ \text{M}^X \\ \xleftarrow{\gamma_{a,\theta}} \end{array} \quad \begin{array}{c} \curvearrowright \\ f \end{array}$$

Whenever  $f(a) = a$ ,  $a \neq \nu f$  for  $a: X \rightarrow \mathbb{M}$

$\Rightarrow \exists \theta \sqsupset 0 \exists x \in X: a(x) + \theta \sqsubseteq \nu f(x)$

$\Rightarrow \emptyset \neq \gamma_{a,\theta}(\nu f) = \nu f_{a,\theta}^\#$

**Contraposition:** If  $\nu f_{a,\theta}^\# = \emptyset$ , then  $a = \nu f$ .

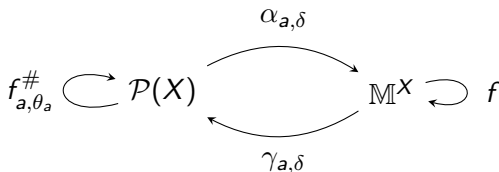
# Galois Connections and Fixpoints

Unfortunately, we do not know this  $\theta$ . But things work fine if we require that for each fixpoint  $a$  there exists  $\theta_a$  such that for each  $\delta$ :

- $\alpha_{a,\theta_a} \circ \gamma_{a,\delta} \circ f \sqsubseteq f \circ \alpha_{a,\theta_a} \circ \gamma_{a,\delta}$

Since we want a proof rule for pre-fixpoints, we need the following requirement ([Condition 2](#)):

- $\alpha_{f(a),\theta_a} \circ \gamma_{f(a),\delta} \circ f \sqsubseteq f \circ \alpha_{a,\theta_a} \circ \gamma_{a,\delta}$



# Proof Rule

## Proof rule

$$\frac{f(a) \sqsubseteq a \quad \nu f_{a, \theta_a}^\# = \emptyset}{\nu f \sqsubseteq a}$$

This proof rule is **sound** and **complete** in the following sense:

Let  $b: X \rightarrow \mathbb{M}$  with  $\nu f \sqsubseteq b$ . Then there exists  $a: X \rightarrow \mathbb{M}$  such that  $a \sqsubseteq b$ ,  $f(a) \sqsubseteq a$  and  $\nu f_a^\# = \emptyset$ .

# Proof Rule

The function  $f^\# = f_{a,\theta_a}^\#$  can usually be defined directly on  $\mathcal{P}(X)$  and can hence be **computed efficiently**. In the case of termination probability:

$$f^\#(Y) = \{x \in Y \mid x \notin T, Q(x) \subseteq Y \cap P_a\}$$

where

- $P_a = \{x \in X \mid a(x) > 0\}$
- $\theta_a = \min\{a(x) \mid x \in X, x \in P_a\}$
- $Q(x) = \{y \in X \mid p_x(y) > 0\}$  for  $x \in X \setminus T$ .

*$f^\#(Y)$  contains those states of  $Y$  that are non-terminating and whose successors are in  $Y$  and have values larger than 0 (i.e. they have the potential for reduction or “slack”).*

# Applications

Despite the restrictions, this approach provides **witnesses** for:

- lower bounds of termination probabilities
- lower bounds for maximal paths
- non-bisimilarity of states
- lower bounds for behavioural distances

It can be used to **iterate to  $\nu f$  from below** (and to iterate to  $\mu f$  from above):

- Perform Kleene iteration starting from  $\perp$  until a fixpoint  $a$  is reached. Test whether it is the greatest fixpoint.
- If it is not, continue with  $a' = a + (\theta_a)_{\nu f_{a, \theta_a}^\#}$ .

This method was developed for the special case of behavioural metrics by [Fu] and [Bacci, Bacci, Larsen, Mardare, Tang, van Breugel]. It gave us the inspiration to look for a generalization.

## Future Work

- Is it possible to lift some of the restrictions? In particular: is it possible to handle partial (instead of total) orders?
- Does it make sense to generalize the Galois connection?
- Compositionality: if  $f, g$  satisfy the requirements, does the same hold for  $f \circ g$ ?