

Joint work with Hernan Melgratti & Christian Roldan

On the semantics of replicated data types

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The quickest background, I

- * Distributed systems replicate their state over different nodes in order to satisfy non-functional requirements.
- Strong consistency (every request receives the most recent update) of replicated data is in conflict with *availability* (every request is eventually executed) and tolerance to network *partitions* (the system operates even in the presence of failures that temporarily prevent communication among components).
- * CAP theorem: it is impossible to simultaneously achieve strong Consistency, Availability and Partition tolerance [GL2002].

The quickest background, II

- * *Weak* consistency: replicas may (temporarily) exhibit discrepancies (every request receives a correct update).
- How are the data specified? States, state transitions and returned values should account for the different views that a data item may simultaneously have.
- * In the end, consistency has to be *eventually* guaranteed (if no new updates are made to a data item, eventually all accesses to that item will return the most recent update).























Aregister



Replicated Data Types

$\mathsf{op}:\mathsf{VIS}\times\mathsf{ARB}\to\mathsf{RVAL}$

- VISibility: A partial order of operations over a replica
- ARBitration: A total order of such operations
- Return VALue: The value returned by the last operation

[BURCKHARDT, GOTSMAN, YANG, ZAWIRSKI 2015]



- Two operations
 - * rd(_,_) = ?
 - $* wr(k)(_,_) = ok$

















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Understanding RDTs

- Implementing RTDs means to provide a communication mechanism among replicas, to ensure its compatibility wrt. the behaviour of the operations and to guarantee that some global properties (e.g. eventual convergence of replicas) are preserved.
- * But first...
 - * Is it possible to get a traditional presentation of RTDs?
 - * Is there any implicit assumption on the arbitrations?
 - * Are RDTs compositional? I.e., are arbitrations of larger visibility orders explained in terms of smaller ones?



,











$$rd \begin{pmatrix} wr(1) & wr(2) & | \\ wr(2) & wr(2) \end{pmatrix} = 2$$

$$\mathcal{S}\left(\begin{array}{cc} \langle \mathtt{wr}(1), \underline{ok} \rangle & \langle \mathtt{wr}(2), \underline{ok} \rangle \\ & \swarrow & \swarrow \\ \langle \mathtt{rd}, 2 \rangle \end{array}\right) = \left\{\begin{array}{cc} \langle \mathtt{wr}(1), ok \rangle \\ | \\ \langle \mathtt{wr}(2), ok \rangle \\ | \\ \langle \mathtt{rd}, 2 \rangle \end{array}\right\}$$



$$rd \begin{pmatrix} wr(2) \\ wr(1) & wr(2) \\ wr(1) \end{pmatrix} = 1$$

$$S\left(\begin{array}{cc} \langle \mathtt{wr}(1), \underline{ok} \rangle & \langle \mathtt{wr}(2), \underline{ok} \rangle \\ & \swarrow & \swarrow \\ & \swarrow & & \\ \langle \mathtt{rd}, \underline{0} \rangle \end{array}\right) = \left\{\begin{array}{c} \\ \\ \end{array}\right\}$$

Recovering RDTs: saturation

$$\begin{array}{ccc} rd \left(\begin{array}{cc} & \texttt{wr(1)} \\ \texttt{wr(1)} & \texttt{wr(2)} \end{array} \right) = 2 \\ & \texttt{wr(2)} \end{array} \end{array}$$

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 $S\left(\begin{array}{c|c} \langle \mathtt{wr}(1), ok \rangle & \langle \mathtt{wr}(2), ok \rangle \\ & \swarrow & \swarrow \\ & \swarrow & & \\ & \langle \mathtt{rd}, 2 \rangle \end{array}\right)$

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value-deterministic: empty intersection (after removing the last event)

 $S\left(\begin{array}{c} \langle \mathtt{wr}(1),ok \rangle & \langle \mathtt{wr}(2),ok \rangle \\ & \swarrow \\ & \swarrow \\ & \langle \mathtt{rd},2 \rangle \end{array}\right)$ $\mathcal{S}\left(\begin{array}{cc} \langle \mathtt{wr}(1),ok\rangle & \langle \mathtt{wr}(2),ok\rangle \\ & \swarrow \\ & \swarrow \\ & \langle \mathtt{rd},1\rangle \end{array}\right)$

value-deterministic: empty intersection (after removing the last event)

deterministic: empty intersection even forgetting the value component

 $S\left(\begin{array}{c} \langle \mathtt{wr}(1),ok \rangle & \langle \mathtt{wr}(2),ok \rangle \\ & \swarrow & \swarrow \\ & \swarrow & & \\ \langle \mathtt{rd},2 \rangle \end{array}\right)$

value-deterministic: empty intersection (after removing the last event) deterministic: empty intersection *even* forgetting the value component

> RTDs have chosen the second path, thus e.g. forbidding write failures

Recovering RDTs: coherence



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$$\forall \mathtt{G}. \ \mathcal{S}(\mathtt{G}) = \bigotimes_{\mathtt{e} \in \mathcal{E}_{\mathtt{G}}} \mathcal{S}(\mathtt{G}|_{-\prec^* \mathtt{e}})$$

Recovering RDTs: coherence



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Admissible arbitrations never increases when extending the visibility

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$$\mathcal{S} \left(\begin{array}{c} \langle \texttt{inc}, \texttt{ok} \rangle \\ \psi \\ \langle \texttt{rd}, 1 \rangle \end{array} \right) = \left\{ \begin{array}{c} \langle \texttt{inc}, \texttt{ok} \rangle \\ | \\ \langle \texttt{rd}, 1 \rangle \end{array} \right\} \quad \mathcal{S} \left(\begin{array}{c} \langle \texttt{inc}, \texttt{fail} \rangle \\ \psi \\ \langle \texttt{rd}, \bot \rangle \end{array} \right) = \left\{ \begin{array}{c} \langle \texttt{inc}, \texttt{fail} \rangle \\ | \\ \langle \texttt{rd}, \bot \rangle \end{array} \right\}$$

value-deterministic, yet not deterministic

From specifications to transition systems



states

From specifications to transition systems

$$\langle {\tt G}, {\tt P}
angle$$
 ${\tt P} \in {\cal S}({\tt G})$

states

$$\langle {\tt G}, {\tt P}
angle \stackrel{\ell}{
ightarrow} \langle {\tt G}', {\tt P}'
angle$$

transitions

$$\mathtt{G}'=\mathtt{G}^\ell$$

$$\mathsf{P}'|_{\mathcal{E}_{\mathsf{G}}} = \mathsf{P}$$

From specifications to transition systems

$$\begin{array}{l} \label{eq:generalized_comp} \\ \frac{\langle \mathsf{G}_1,\mathsf{P}|_{\pounds_{\mathsf{G}_1}}\rangle \stackrel{\ell}{\to} \langle \mathsf{G}_1',\mathsf{P}_1'\rangle \qquad \mathsf{P}'\in\mathsf{P}\otimes\mathsf{P}_1'}{\langle \mathsf{G}_1\sqcup\mathsf{G}_2,\mathsf{P}\rangle \stackrel{\ell}{\to} \langle \mathsf{G}_1'\sqcup\mathsf{G}_2,\mathsf{P}'\rangle} \end{array}$$

an abstract transition system against which to compare (by asynchronous simulation) those of actual implementations...

Implementing a specification

- * Proposed implementation of RDTs [Burckhardt et al.].
 - * Each replica propagates its state to the other replicas.
 - * It is assumed that all replicas have the same behaviour.









an LTS for a counter

$$\Sigma = \mathcal{R} imes (\mathcal{R} \mapsto \mathbb{N})$$

 $\mathcal{L} = \{ \langle \texttt{inc}, \texttt{ok} \rangle \} \cup (\{\texttt{rd}\} imes \mathbb{N})$

(READ)

(INC)

 $\frac{\mathbf{k} = \Sigma_{\mathbf{s} \in dom(\mathbf{v})} \mathbf{v}(\mathbf{s})}{\langle \mathbf{r}, \mathbf{v} \rangle \xrightarrow{\mathbf{rd}, \mathbf{k}} \langle \mathbf{r}, \mathbf{v} \rangle}$ $\langle \mathbf{r}, \mathbf{v} \rangle \xrightarrow{\texttt{inc}, \texttt{ok}} \langle \mathbf{r}, \mathbf{v} [\mathbf{r} \mapsto \mathbf{v} (\mathbf{r}) + \mathbf{1}] \rangle$

an LTS for a counter

(SEND) (RCV)

$$\langle \mathbf{r}, \mathbf{v} \rangle \xrightarrow{\text{send}, \langle \mathbf{r}, \mathbf{v} \rangle} \langle \mathbf{r}, \mathbf{v} \rangle \qquad \langle \mathbf{r}, \mathbf{v} \rangle \xrightarrow{\mathbf{rcv}, \langle \mathbf{r}_k, \mathbf{v}_k \rangle} \langle \mathbf{r}, \max\{\mathbf{v}, \mathbf{v}_k\} \rangle$$

 $\forall s. \max\{\mathbf{v}, \mathbf{v}_k\} (s) = \max\{\mathbf{v}(s), \mathbf{v}_k(s)\}$

the resulting LTS is correct wrt. the abstract LTS (via a suitable simulation)

an LTS for multiple counters

$$(SEND) \qquad (RCV) \\ \langle \mathbf{r}, \mathbf{v} \rangle \xrightarrow{\text{send}, \langle \mathbf{r}, \mathbf{v} \rangle} \langle \mathbf{r}, \mathbf{v} \rangle \qquad \langle \mathbf{r}, \mathbf{v} \rangle \xrightarrow{\mathbf{rcv}, \langle \mathbf{r}_k, \mathbf{v}_k \rangle} \langle \mathbf{r}, \max\{\mathbf{v}, \mathbf{v}_k\} \rangle \\ (PARL) \qquad (COMM) \\ \frac{\sigma_1 \xrightarrow{\ell} \sigma_1'}{\sigma_1 \| \sigma_2 \xrightarrow{\ell} \sigma_1' \| \sigma_2} \qquad \frac{\sigma_1 \xrightarrow{\text{send}, \sigma} \sigma_1' \quad \sigma_2 \xrightarrow{\mathbf{rcv}, \sigma} \sigma_2'}{\sigma_1 \| \sigma_2 \xrightarrow{\tau} \sigma_1' \| \sigma_2'} \\ \end{cases}$$

the resulting LTS is still correct wrt. the abstract LTS

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 - * thus making explicit some implicit assumptions
- * ...& a mechanism for proving correctness of implementations
- We are looking for a categorical presentation
 - …in order to get operators for composing specifications
- We plan to recast guarantee properties via the abstract LTS